

SERVO VALVES

TWO STAGE MECHANICAL FEEDBACK VALVE SIZE 04 ISO 10372 (62 SERIES)

Rev. L, May 2024

FOR DEPENDABLE, LONG LIFE OPERATION
WHERE POSITION, L SPEED, PRESSURE OR
FORCECONTROSYSTEMS HAVE HIGH
DYNAMIC RESPONSE REQUIREMENTS

62 SERIES TWO STAGE SERVO VALVES

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The 62 Series flow control servovalves are throttle valves for 3- and preferably 4-way applications. They are a standard performance, two-stage design that covers the range of rated flows from 2.5 to 20 gpm at 1000 psi valve drop. The output stage is a closed center, fourway sliding spool. The pilot stage is a symmetrical double nozzle and flapper, driven by a double air gap, dry torque motor. Mechanical feedback of spool position is provided by a cantilever spring. The valve design is simple and rugged

for dependable, long life operation. These valves are suitable for electrohydraulic position, speed, pressure or force control systems with high dynamic response requirements.

Principle of operation

An electrical command signal (flow rate set point) is applied to the torque motor coils, and creates a magnetic force which acts on the ends of the pilot stage armature. This causes a deflection of the armature/flapper assembly within the flexure tube.

Deflection of the flapper restricts fluid flow through one nozzle which is carried through to one spool end, displacing the spool.

Movement of the spool opens the supply pressure port (P) to one control port, while simultaneously opening the tank port (T)/return port (R) to the other control port. The spool motion also applies a force to the cantilever spring, creating a restoring torque on the armature/flapper assembly.

Once the restoring torque becomes equal to the torque from the magnetic forces, the armature/flapper assembly moves back to the neutral position, and the spool is held open in a state of equilibrium until the command signal changes to a new level.

In summary, the spool position is proportional to the input current and with constant pressure drop across the valve, flow to the load is proportional to the spool position.

VALVE FEATURES

- 2-stage design with dry torque motor
- Low friction double nozzle pilot stage
- High spool control forces
- High dynamics
- Low cost design
- Rugged, long-life design
- High resolution, low hysteresis
- Completely set-up at the factory

The actual flow is dependent upon electrical command signal and valve pressure drop. The flow for a given valve pressure drop can be calculated using the square root function for sharp edge orifices:

$$Q = Q_N \sqrt{\frac{\Delta p}{\Delta p_N}}$$

Q [gpm] = calculated flow

Q_N [gpm] = rated flow

Δp [psi] = actual valve pressure drop

Δp_N [psi] = rated valve pressure drop



This catalog is for users with technical knowledge. To ensure that all necessary characteristics for function and safety of the system are given, the user has

to check the suitability of the products described here. In case of doubt, please contact Moog Inc.

**62 SERIES
GENERAL TECHNICAL DATA**

Operating Pressure
 ports P, A/1, and B/2 up to 3,000 psi
 port T/R up to 2,000 psi

Temperature Range
 Fluid 0°F to 200°F
 Ambient 0°F to 200°F

Seal Material
 Viton, others on request

Operating Fluid
 Compatible with common hydraulic fluids, other fluids on request.

Recommended viscosity 60-450 SUS @ 100°F

System Filtration: High pressure filter (without bypass, but with dirt alarm) mounted in the main flow and if possible, directly upstream of the valve.

Class of Cleanliness: The cleanliness of the hydraulic fluid greatly effects the performance (spool positioning, high resolution) and wear (metering edges, pressure gain, leakage) of the servovalve.

Recommended Cleanliness Class
 For normal operation ISO 4406 < 14/11
 For longer life ISO 4406 < 13/10

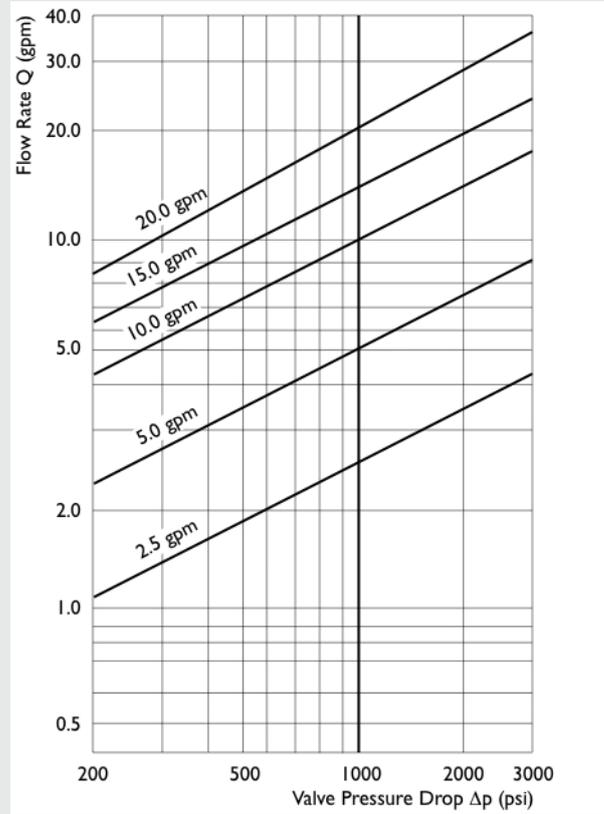
Filter Rating Recommended
 For normal operation $\beta_{10} \rightarrow 75$ (10 μ m absolute)
 For longer life $\beta_5 \rightarrow 75$ (5 μ m absolute)

Installation Operations Any position, fixed or moveable.

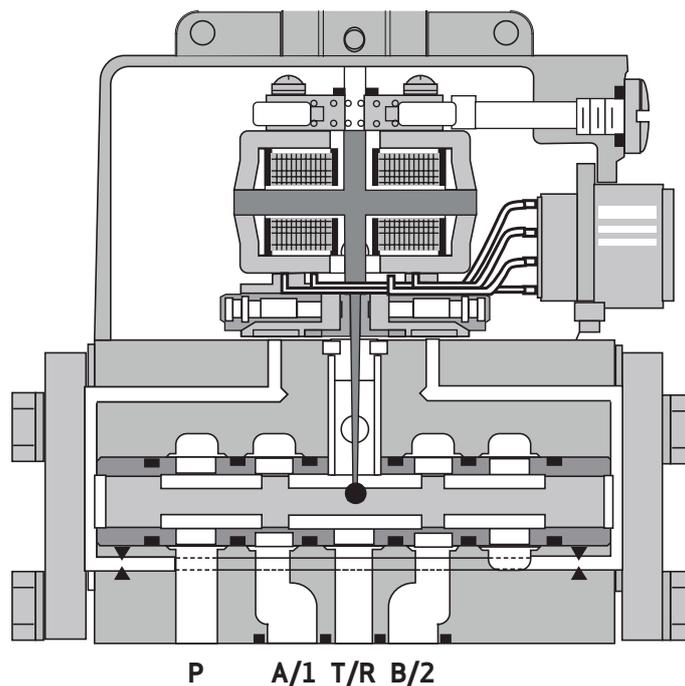
Vibration 30 g, 3 axes

Weight 2.7 lb. (1.2 kg)

Shipping Plate Delivered with an oil sealed shipping plate



Valve Flow Diagram
 Valve flow for maximum valve opening (100% command signal) as a function of the valve pressure drop.



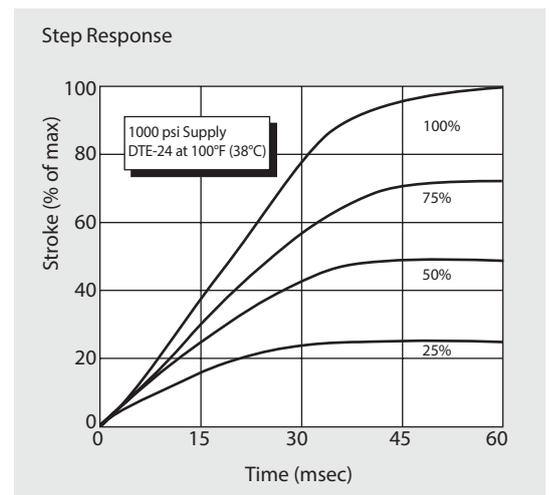
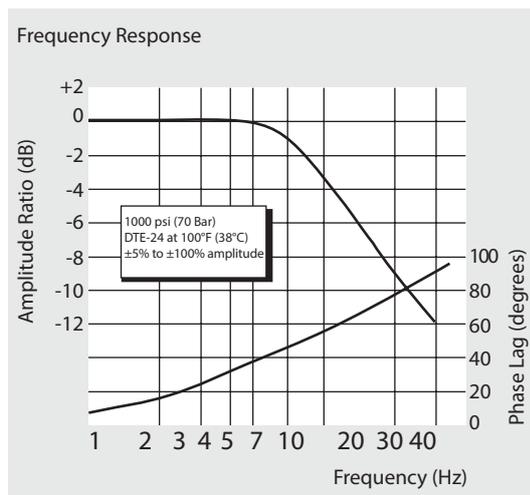
62 SERIES TECHNICAL DATA

Model...Type	62
Mounting Pattern	ISO 10372 - 04-04-0-92
Valve Body Version	4-way 2-stage with spool busing design
Pilot Stage	Nozzle/Flapper, High flow
Pilot Connection	Internal only

Rated Flow	(±10%) at $\Delta p_N = 1,000$ ps	[gpm]	2.5	5.0	10.0	15.0	20.0
Response Time*		[ms]	60	60	60	60	60
Threshold*		[%]			<1%		
Hysteresis*		[%]			<5%		
Null Shift	at $\Delta T = 100^\circ\text{F}$	[%]			<5%		
Null Leakage Flow	max.	[gpm]			0.35 TO 0.55		

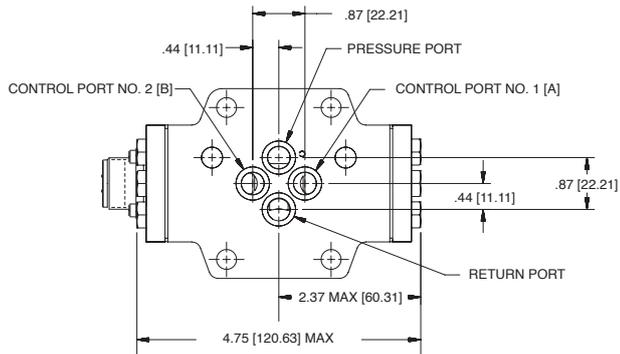
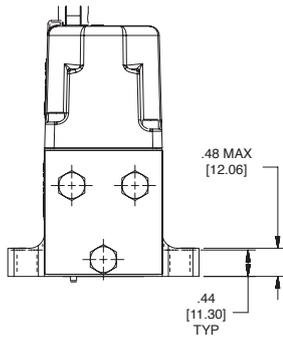
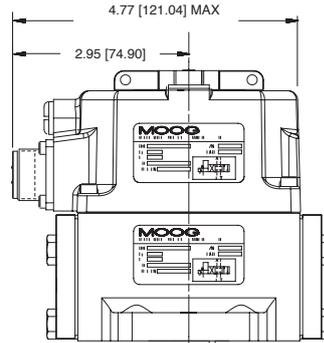
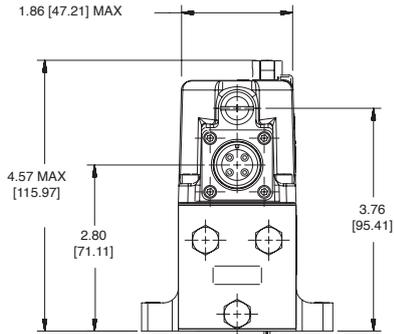
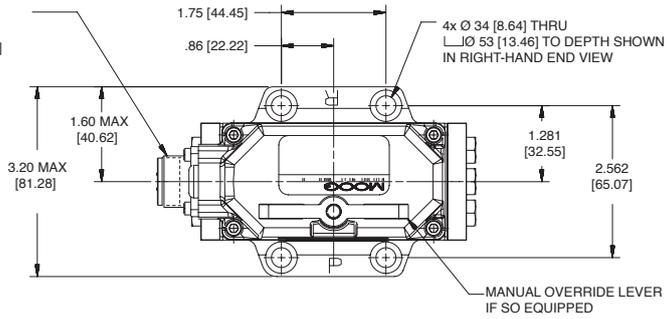
* Measured at 1,000 psi operating pressure

Typical characteristic curves with ±5% to ±100% input signal, measured at 1,000 psi operating pressure.

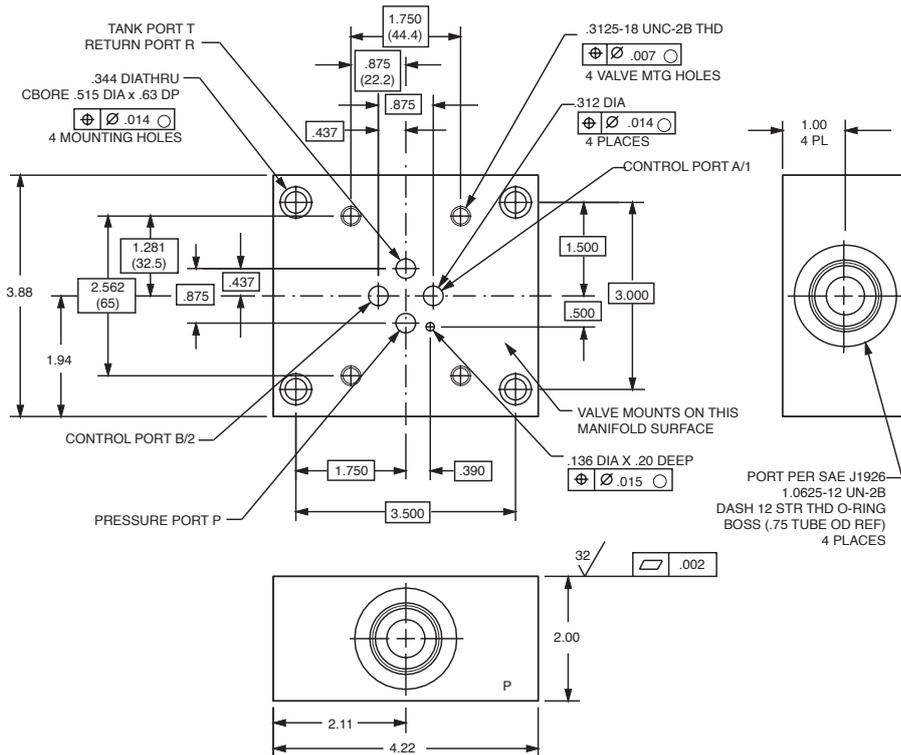


**62 SERIES
INSTALLATION DRAWINGS**

ELECTRICAL CONNECTOR MATES WITH MS 3106-14S-2S SHOWN OVER CONTROL PORT [B] (ALTERNATE CONSTRUCTION OVER CONTROL PORT 1 [A])



TYPICAL SUBPLATE MANIFOLD



Null Adjust: Flow out of Control Port B will increase with clockwise rotation of null adjust screw (1/8 hex key).

The mounting manifold must conform to ISO 10372-04-04-0-92
Surface to which valve is mounted requires a $\sqrt{32}$ [ΔΔ] finish, flat within 0.002 [0.05] TIR.

62 SERIES MOUNTING REQUIREMENTS

Recommended Mounting Seals

Material dependant on application

- 1.78 mm (0.070 in) cross-section x 10.82 mm (0.426 in) inside diameter, 90 durometer
- Equivalent AS83248/2 size -013

Recommended Mounting Screws

Material dependant on application

- SHCS 5/16 x 1.0 long. Grade 8 minimum
- SHCS M8 x 25 long. Grade 10.9 minimum

ELECTRICAL CONNECTIONS

Rated current and coil resistance

Two different coil designs are available for 62 Series Servovalves. See Table 1.

Coil connections

A four-pin electrical connector (that mates with an MS3106R14S-2S) is standard. All four torque motor leads are available at the connector so external connections can be made for series, parallel or differential operation.

Servoamplifier

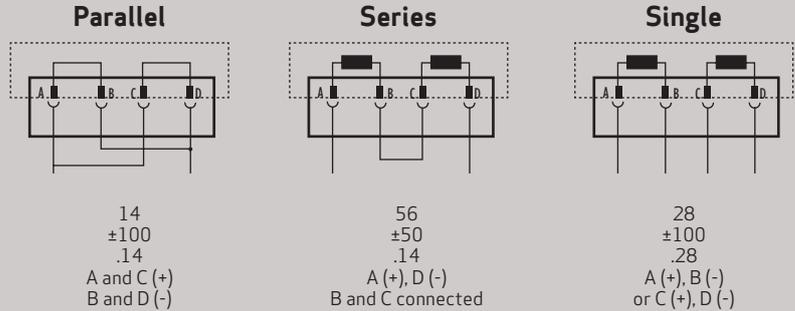
The servovalve responds to input current, therefore a servoamplifier that has high internal impedance (as obtained with current feedback) should be used. This will reduce the effects of coil inductance and will minimize changes due to coil resistance variations.

ELECTRICAL CONNECTIONS

(Example with typical 62 series coils)

Coil Resistance
Rated Current
Electrical Power
Connections for Valve Opening
P↗B, A↘T

[Ω]
[mA]
[W]



Note: Before applying electrical signals, the pilot stage has to be pressurized.

TABLE 1

Nominal Resistance Per Coil at 77°F (25°C) Ω	Recommended Rated Current-mA		Approximate Coil Inductance*-Henrys		
	Parallel, Differential or Single Coil Operation	Series Coils	Single Coils	Series Coils	Parallel Coils
28	100	50	0.2	0.8	0.2
300	30	15	2	7	2

* Measured at 50 Hz.

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